Advanced Systems Lab

Spring 2024

Lecture: Memory hierarchy, locality, caches

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ETH

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Organization

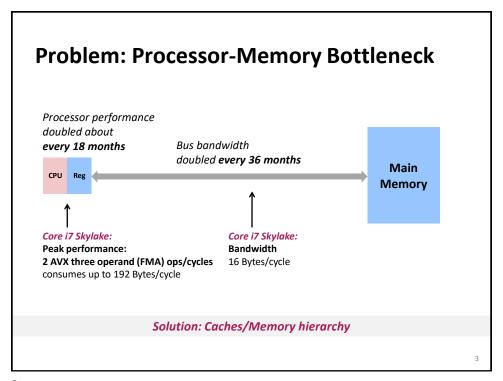
Temporal and spatial locality

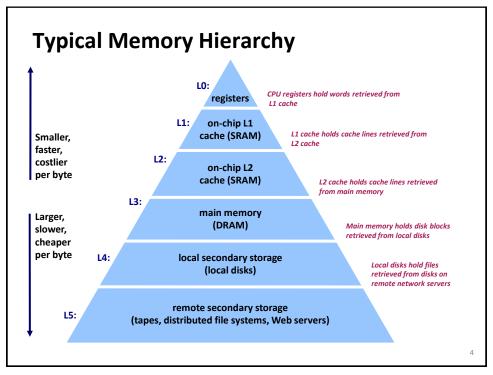
Memory hierarchy

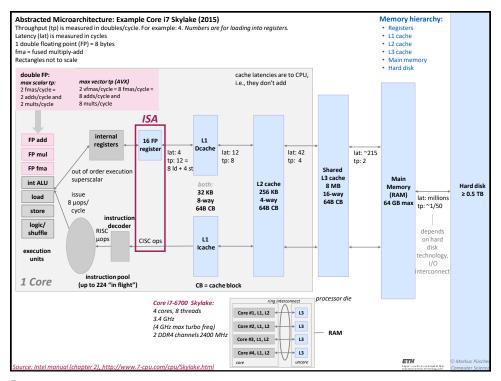
Caches

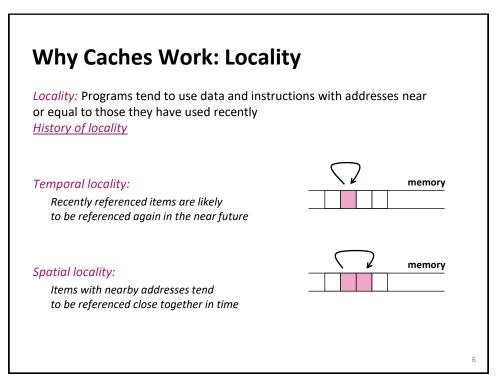
Chapter 5 in Computer Systems: A Programmer's Perspective, 2nd edition, Randal E. Bryant and David R. O'Hallaron, Addison Wesley 2010 Part of these slides are adapted from the course associated with this book

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Example: Locality?

```
sum = 0;
for (i = 0; i < n; i++)
sum += a[i];
return sum;
```

Data:

- Temporal: **sum** referenced in each iteration
- Spatial: array a[] accessed consecutively

Instructions:

- Temporal: loops cycle through the same instructions
- Spatial: instructions referenced in sequence

Being able to assess the locality of code is a crucial skill for a performance programmer

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Locality Example #1

```
int sum_array_rows(double a[M][N])
{
  int i, j; double sum = 0;

  for (i = 0; i < M; i++)
    for (j = 0; j < N; j++)
        sum += a[i][j];
  return sum;
}</pre>
```

Locality Example #2

```
int sum_array_3d(double a[K][M][N])
{
  int i, j, k; double sum = 0;

  for (i = 0; i < M; i++)
    for (j = 0; j < N; j++)
    for (k = 0; k < K; k++)
        sum += a[k][i][j];
  return sum;
}</pre>
```

How to improve locality?

Performance [flops/cycle]

0.4

0.35

0.3

0.25

0.2

0.15

CPU: Intel(R) Core(TM) i7-4980HQ CPU @ 2.80GHz gcc: Apple LLVM version 8.0.0 (clang-800.0.42.1) flags: -O3 -fno-vectorize

Why the peaks?
Answer later

8 24 M = N = K

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Operational Intensity Again

Definition: Given a program P, assume cold (empty) cache

Operational intensity:
$$I(n) = \frac{W(n)}{Q(n)}$$
 #flops (input size n)

#bytes transferred cache \leftrightarrow memory (for input size n)

O(n)

Examples: Determine asymptotic bounds on I(n)

Vector sum: y = x + y
 Matrix-vector product: y = Ax
 O(1)

Matrix-vector product: y = Ax
 Fast Fourier transform
 O(log(n))

Matrix-matrix product: C = AB + C

Compute/Memory Bound

A function/piece of code is:

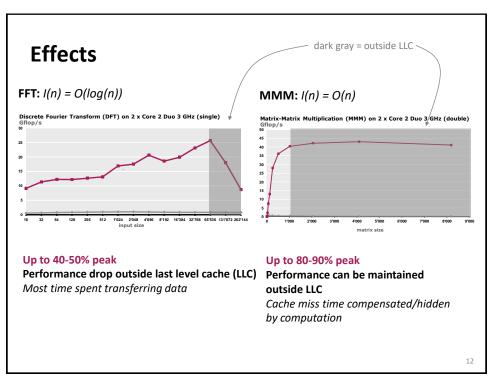
- Compute bound if it has high operational intensity
- Memory bound if it has low operational intensity

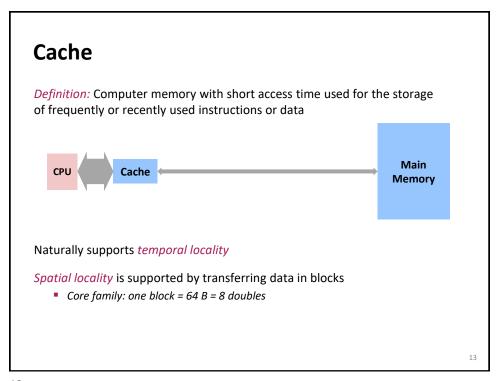
Relationship between operational intensity and locality?

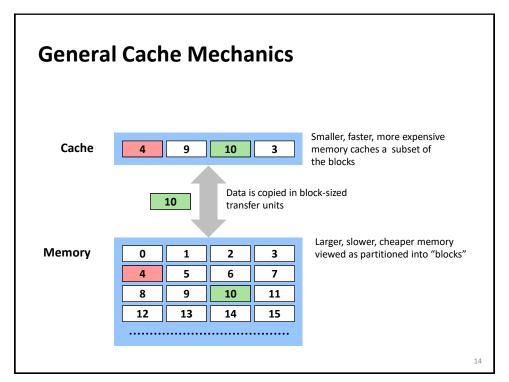
- They are closely related
- Operational intensity only describes the boundary last level cache/memory

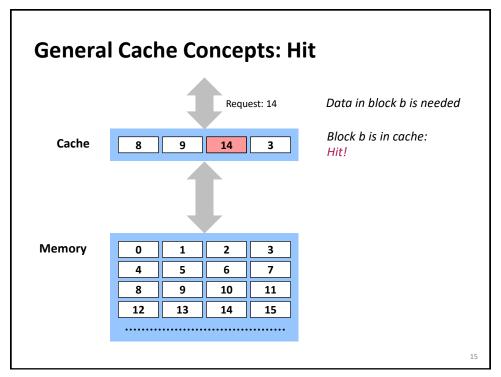
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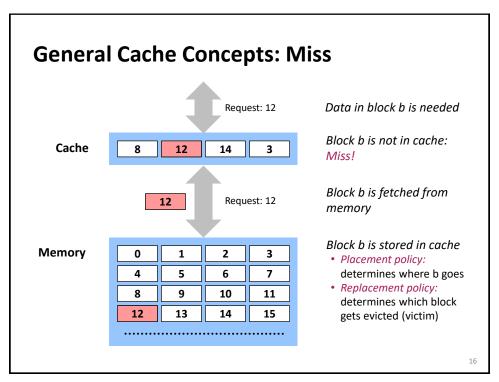
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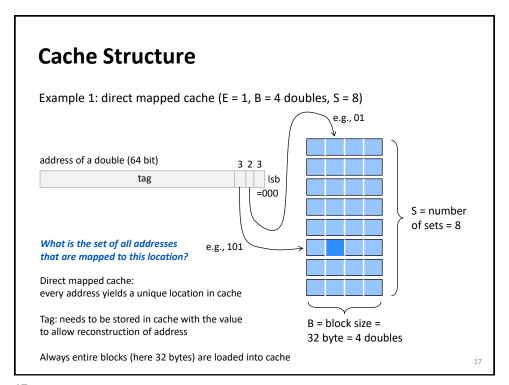


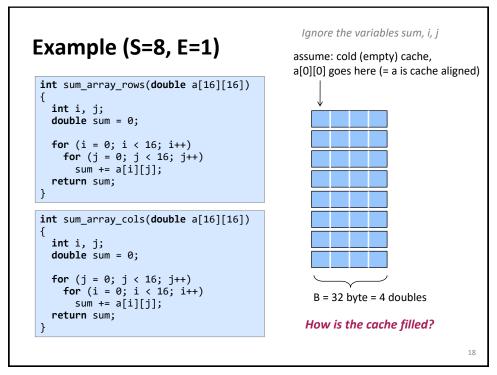


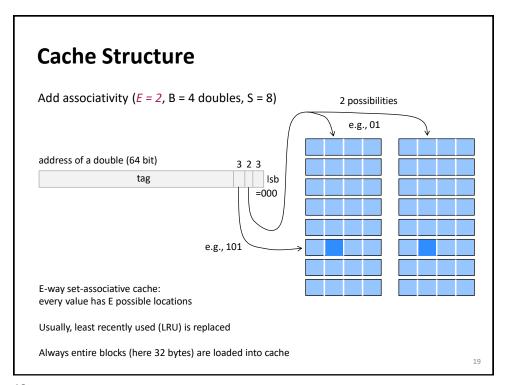


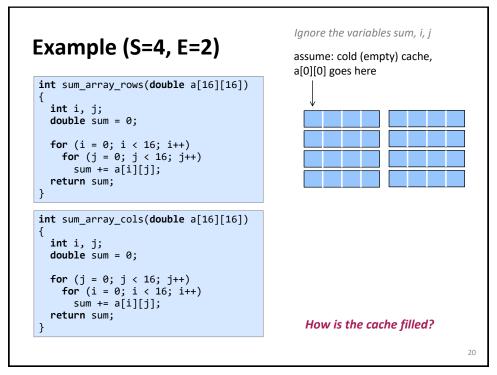


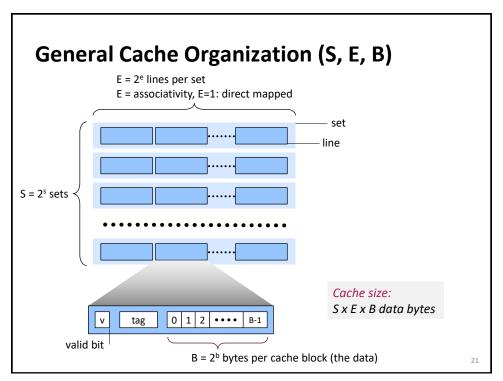


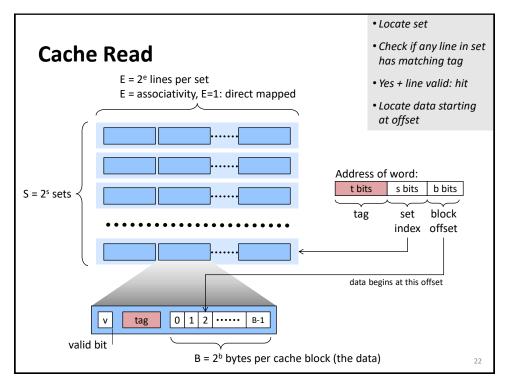












Types of Cache Misses (The 3 C's)

Compulsory (cold) miss

Occurs on first access to a block

Capacity miss

Occurs when working set is larger than the cache

Conflict miss

Conflict misses occur when the cache is large enough, but multiple data objects all map to the same slot

Not a clean classification but still useful

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Terminology

Direct mapped cache:

- Cache with E = 1
- Means every block from memory has a unique location in cache

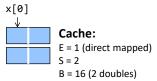
Fully associative cache

- Cache with S = 1 (i.e., maximal E)
- Means every block from memory can be mapped to any location in cache
- In practice to expensive to build
- One can view the register file as a fully associative cache

LRU (least recently used) replacement

 When selecting which block should be replaced (happens only for E > 1), the least recently used one is chosen

Small Example, Part 1



Array (accessed twice in example)

x = x[0], ..., x[7]

% Matlab style code
for j = 0:1
 for i = 0:7
 access(x[i])

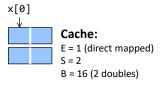
Access pattern: 0123456701234567
Hit/Miss: MHMHMHMHMHMHMHMH

Result: 8 misses, 8 hits Spatial locality: yes Temporal locality: no

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Small Example, Part 2



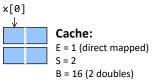
Array (accessed twice in example)

x = x[0], ..., x[7]

% Matlab style code
for j = 0:1
 for i = 0:2:7
 access(x[i])
 for i = 1:2:7
 access(x[i])

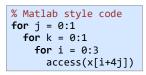
Result: 16 misses Spatial locality: no Temporal locality: no

Small Example, Part 3



Array (accessed twice in example)

x = x[0], ..., x[7]



Access pattern: 0123012345674567 Hit/Miss: MHMHHHHHHHHHHH

Result: 4 misses, 12 hits (is optimal, why?)

Spatial locality: yes **Temporal locality:** yes

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Cache Performance Metrics

Miss rate

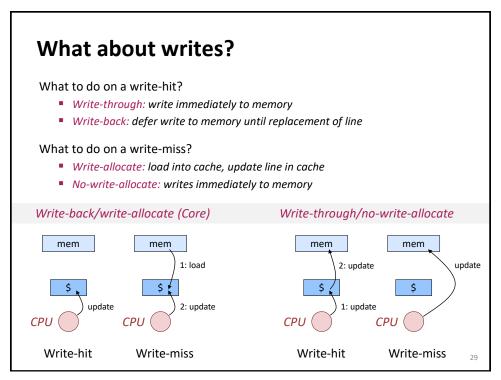
Fraction of memory references not found in cache: misses / accesses
 = 1 - hit rate

Hit time

- Time (latency) to deliver a block in the cache to the processor
- Skylake: 4 clock cycles for L1 12 clock cycles for L2

Miss penalty

- Additional time required because of a miss
- Skylake: about 200 cycles for L3 miss



Example:

z = x + y, x, y, z vector of doubles of length n

assume they fit jointly in cache + cold cache

memory traffic Q(n): 4n doubles = 32n bytes

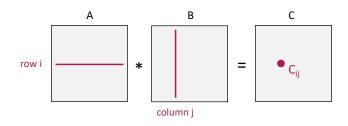
operational intensity I(n)? W(n) = n flops, so

I(n) = W(n)/Q(n) = 1/32

Locality Optimization: Blocking

Example: MMM

```
void mmm(double *A, double *B, double *C, int n) {
  for( int i = 0; i < n; i++ )
    for( int j = 0; j < n; j++ )
    for( int k = 0; k < n; k++ )
        C[n*i + j] = C[n*i + j] + A[n*i + k] * B[n*k + j]; }</pre>
```



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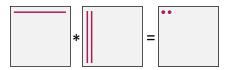
Cache Miss Analysis MMM

C = A*B, all $n \times n$

Assumptions: cache size y << n, cache block: 8 doubles, only 1 cache, row-major order

Triple loop:

Blocked (six-fold loop): block size b, 8 divides b



1. entry: n/8 + n = 9n/8 cache misses

 $n^2 * 9n/8 = 9n^3/8$

1. block: nb/8 + nb/8 = nb/4 cache misses

2. entry: same 2. block: same

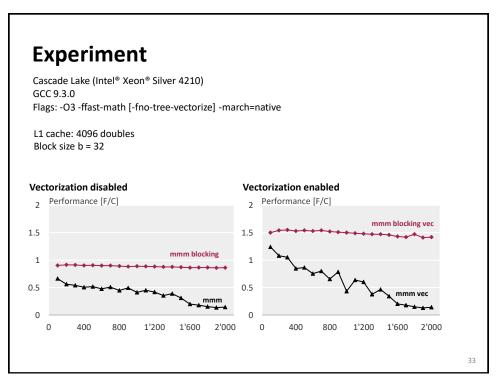
Total: $(n/b)^2 * nb/4 = n^3/(4b)$

How to choose h

Total:

The above analysis assumes that the multiplication of b x b blocks can be done with only compulsory misses. This is achieved with $3b^2 \le \gamma$.

b = sqrt(γ /3) which yields about sqrt(3)/(4*sqrt(γ)) * n³ cache misses, a gain of \approx 2.6*sqrt(γ) I(n) = O(sqrt(γ))



On MMM Cache Analysis

Refine the analysis by including the misses incurred by C

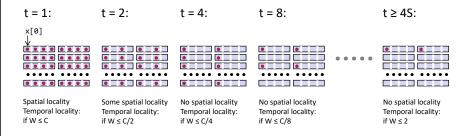
Compute the operational intensity in both cases

Try an analogous analysis for matrix-vector multiplication

The Killer: Two-Power Strided Working Sets

```
% t = 1,2,4,8,... a 2-power
% size W of working set: W = n/t
for (i = 0; i < n; i += t)
  access(x[i])
for (i = 0; i < n; i += t)
  access(x[i])</pre>
```

Cache: E = 2, B = 4 doubles



Working with a two-power-strided working set is like having a smaller cache

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The Killer: Where Can It Occur?

Accessing two-power size 2D arrays (e.g., images) columnwise

- 2d Transforms
- Stencil computations
- Correlations

Various transform algorithms

- Fast Fourier transform
- Wavelet transforms
- Filter banks

Example from Before

```
int sum_array_3d(double a[K][M][N])
{
   int i, j, k, sum = 0;
   for (i = 0; i < M; i++)
        for (k = 0; k < K; k++)
            sum += a[k][i][j];
   return sum;
}

Performance [flops/cycle]

CPU: Intel(R) Core(TM) i7-4980HQ CPU @ 2.80GHz gcc: Apple LLVM version 8.0.0 (clang-800.0.42.1) flags: -03 -fno-vectorize

CPU: Intel(R) Core(TM) i7-4980HQ CPU @ 2.80GHz gcc: Apple LLVM version 8.0.0 (clang-800.0.42.1) flags: -03 -fno-vectorize

2-power strides</pre>
```

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Summary

It is important to assess temporal and spatial locality in the code

 $\begin{array}{c} 1 & 8 \\ 1 & 6$

Cache structure is determined by three parameters

- block size
- number of sets
- associativity

You should be able to roughly simulate a computation on paper

Blocking to improve locality

Two-power strides can be problematic (conflict misses)

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