

Advanced Systems Lab

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Lecture: Optimizing FFT, FFTW

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Fast FFT: Example FFTW Library

- www.fftw.org
- Frigo and Johnson, *FFTW: An Adaptive Software Architecture for the FFT*, ICASSP 1998
- Frigo, *A Fast Fourier Transform Compiler*, PLDI 1999
- Frigo and Johnson, *The Design and Implementation of FFTW3*, Proc. IEEE 93(2) 2005

Recursive Cooley-Tukey FFT

$$\text{DFT}_{km} = (\text{DFT}_k \otimes \text{I}_m) T_m^{km} (\text{I}_k \otimes \text{DFT}_m) L_k^{km} \quad \text{decimation-in-time}$$

$$\text{DFT}_{km} = L_m^{km} (\text{I}_k \otimes \text{DFT}_m) T_m^{km} (\text{DFT}_k \otimes \text{I}_m) \quad \text{decimation-in-frequency}$$

- For powers of two $n = 2^t$ sufficient together with base case

$$\text{DFT}_2 = \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix}$$

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Cooley-Tukey FFT, $n = 4$

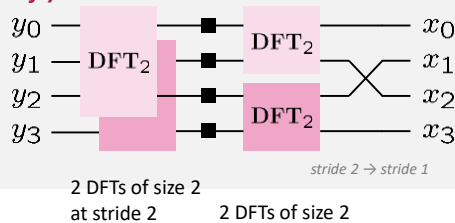
Fast Fourier transform (FFT)

$$\begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & i & -1 & -i \\ 1 & -1 & 1 & -1 \\ 1 & -i & -1 & i \end{bmatrix} = \begin{bmatrix} 1 & \cdot & 1 & \cdot \\ \cdot & 1 & \cdot & 1 \\ 1 & \cdot & -1 & \cdot \\ \cdot & 1 & \cdot & -1 \end{bmatrix} \begin{bmatrix} 1 & \cdot & \cdot & \cdot \\ \cdot & 1 & \cdot & \cdot \\ \cdot & \cdot & 1 & \cdot \\ \cdot & \cdot & \cdot & i \end{bmatrix} \begin{bmatrix} 1 & 1 & \cdot & \cdot \\ 1 & -1 & \cdot & \cdot \\ \cdot & \cdot & 1 & 1 \\ \cdot & \cdot & 1 & -1 \end{bmatrix} \begin{bmatrix} 1 & \cdot & \cdot & \cdot \\ \cdot & \cdot & 1 & \cdot \\ \cdot & 1 & \cdot & \cdot \\ \cdot & \cdot & \cdot & 1 \end{bmatrix}$$

Representation using matrix algebra

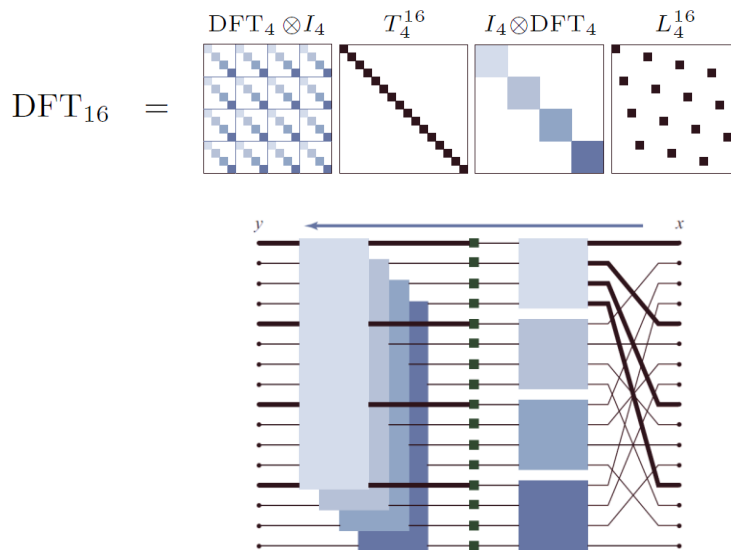
$$\text{DFT}_4 = (\text{DFT}_2 \otimes \text{I}_2) \text{diag}(1, 1, 1, i) (\text{I}_2 \otimes \text{DFT}_2) L_2^4$$

Data flow graph (right to left)



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FFT, $n = 16$ (Recursive, Radix 4)



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Fast Implementation (\approx FFTW 2.x)

- Choice of algorithm
- Locality optimization
- Constants
- Fast basic blocks
- Adaptivity

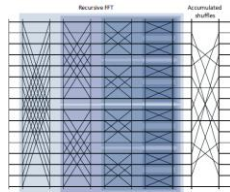
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1: Choice of Algorithm

- Choose recursive, not iterative

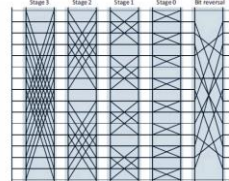
$$\text{DFT}_{km} = (\text{DFT}_k \otimes \text{I}_m) T_m^{km} (\text{I}_k \otimes \text{DFT}_m) L_k^{km}$$

Radix 2, recursive



$$(\text{DFT}_2 \otimes \text{I}_8) T_8^{16} \left(\text{I}_2 \otimes \left((\text{DFT}_2 \otimes \text{I}_4) T_4^{16} \left(\text{I}_2 \otimes ((\text{DFT}_2 \otimes \text{I}_2) T_2^{16} (\text{I}_2 \otimes \text{DFT}_2) L_2^{16}) \right) \right) \right) L_2^{16}$$

Radix 2, iterative



$$\left((\text{I}_1 \otimes \text{DFT}_2 \otimes \text{I}_8) D_8^{16} \right) \left((\text{I}_2 \otimes \text{DFT}_2 \otimes \text{I}_4) D_4^{16} \right) \left((\text{I}_4 \otimes \text{DFT}_2 \otimes \text{I}_2) D_2^{16} \right) \left((\text{I}_8 \otimes \text{DFT}_2 \otimes \text{I}_1) D_1^{16} \right) R_2^{16}$$

First recursive implementation we consider in this course

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2: Locality Improvement

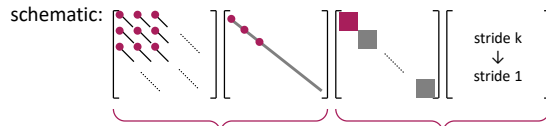
$$\text{DFT}_{16} = \begin{matrix} \text{DFT}_4 \otimes \text{I}_4 & T_4^{16} & \text{I}_4 \otimes \text{DFT}_4 & L_4^{16} \end{matrix}$$

- **Straightforward implementation: 4 steps**
 - Permute
 - Loop recursively calling smaller DFTs (here: 4 of size 4)
 - Loop that scales by twiddle factors (diagonal elements of T)
 - Loop recursively calling smaller DFTs (here: 4 of size 4)
- **4 passes through data: bad locality**
- **Better: fuse some steps**

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2: Locality Improvement

$$\text{DFT}_n = (\text{DFT}_k \otimes \text{I}_m) \text{T}_m^n (\text{I}_k \otimes \text{DFT}_m) \text{L}_k^n$$



fuse: stage 2

- compute m many $\text{DFT}_k \cdot D$ with input stride m and output stride m
- D is part of the diagonal T
- writes to the same location then it reads from \rightarrow in-place

Interface needed for recursive call:

$\text{DFTscaled}(k, x, d, m);$
 ↑ ↑ ↑ ↑
 DFT size input = output stride
 output vector diagonal elements

Cannot handle further recursion so in FFTW it is a base case of the recursion

fuse: stage 1



- compute k many DFT_m with input stride k and output stride 1
- writes to different location then it reads from \rightarrow out-of-place

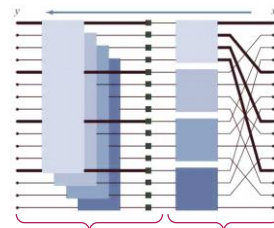
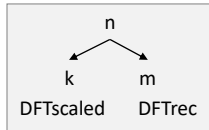
Interface needed for recursive call:

$\text{DFTrec}(m, x, y, k, 1);$
 ↑ ↑ ↑ ↑ ↑
 DFT size input/output vector input stride output stride

Can handle further recursion (just strides change)

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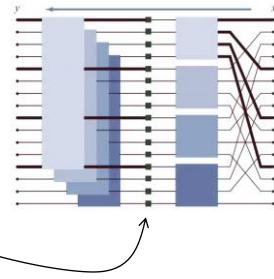
$$\text{DFT}_{km} = \underbrace{(\text{DFT}_k \otimes \text{I}_m) \text{T}_m^{km}}_{\text{one loop}} \underbrace{(\text{I}_k \otimes \text{DFT}_m) \text{L}_k^{km}}_{\text{one loop}}$$



```
// code sketch
void DFT(int n, cpx *x, cpx *y) {
    ...
    int k = choose_dft_radix(n); // ensure k small enough
    int m = n/k;
    for (int i = 0; i < k; ++i)
        DFTrec(m, x + i, y + m*i, k, 1); // implemented as DFT(...) is
    for (int j = 0; j < m; ++j)
        DFTscaled(k, y + j, t[j], m); // always a base case
}
```

3: Constants

- FFT incurs multiplications by roots of unity
- In real arithmetic:
Multiplications by sines and cosines, e.g.,
`y[i] = sin(i*pi/128)*x[i];`
- Very expensive!



- **Observation:** Constants depend only on input size, not on input
- **Solution:** Precompute once and use many times

```
d = DFT_init(1024); // init function computes constant table
d(x, y);           // use many times
```

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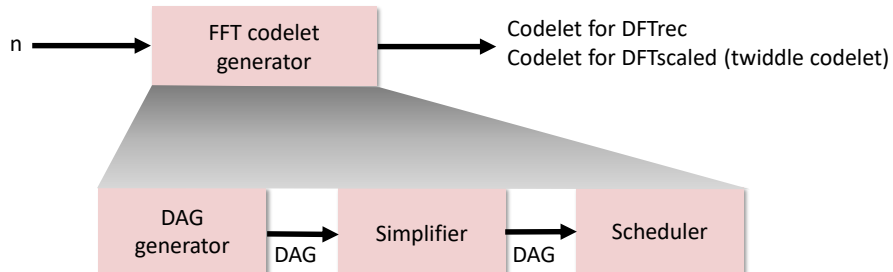
4: Optimized Basic Blocks

```
// code sketch
void DFT(int n, cpx *x, cpx *y) {
    if (use_base_case(n))
        DFTbc(n, x, y); // use base case
    else {
        int k = choose_dft_radix(n); // ensure k <= 32
        int m = n/k;
        for (int i = 0; i < k; ++i)
            DFTrec(m, x + i, y + m*i, k, 1); // implemented as DFT(...) is
        for (int j = 0; j < m; ++j)
            DFTscaled(k, y + j, t[j], m); // always a base case
    }
}
```

- Just like loops can be unrolled, recursions can also be unrolled
- Empirical study: Base cases for sizes $n \leq 32$ useful (scalar code)
- Needs 62 base cases or “codelets” (why?)
 - DFTrec, sizes 2–32
 - DFTscaled, sizes 2–32
- **Solution:** Codelet generator (codelet = optimized basic block)

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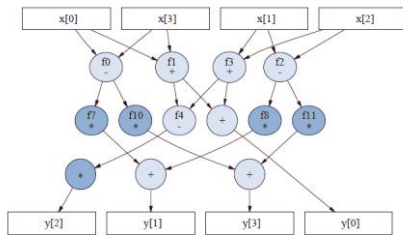
FFTW Codelet Generator



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Small Example DAG

DAG:



One possible unparsing:

```

f0 = x[0] - x[3];
f1 = x[0] + x[3];
f2 = x[1] - x[2];
f3 = x[1] + x[2];
f4 = f1 - f3;
y[0] = f1 + f3;
y[2] = 0.7071067811865476 * f4;
f7 = 0.9238795325112867 * f0;
f8 = 0.3826834323650898 * f2;
y[1] = f7 + f8;
f10 = 0.3826834323650898 * f0;
f11 = (-0.9238795325112867) * f2;
y[3] = f10 + f11;
  
```

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DAG Generator



- **Knows FFTs: Cooley-Tukey, split-radix, Good-Thomas, Rader, represented in sum notation**

$$y_{n_2 j_1 + j_2} = \sum_{k_1=0}^{n_1-1} \left(\omega_n^{j_2 k_1} \right) \left(\sum_{k_2=0}^{n_2-1} x_{n_1 k_2 + k_1} \omega_{n_2}^{j_2 k_2} \right) \omega_{n_1}^{j_1 k_1}$$

- **For given n, suitable FFTs are recursively applied to yield n (real) expression trees for outputs y_0, \dots, y_{n-1}**
- **Trees are fused to an (unoptimized) DAG**

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Simplifier



- **Applies:**
 - Algebraic transformations
 - Common subexpression elimination (CSE)
 - DFT-specific optimizations
- **Algebraic transformations**
 - Simplify mults by 0, 1, -1
 - Distributivity law: $kx + ky = k(x + y)$, $kx + lx = (k + l)x$
Canonicalization: $(x-y)$, $(y-x)$ to $(x-y)$, $-(x-y)$
- **CSE: standard**
 - E.g., two occurrences of $2x+y$: assign new temporary variable
- **DFT specific optimizations**
 - All numeric constants are made positive (reduces register pressure)
 - CSE also on transposed DAG

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Scheduler

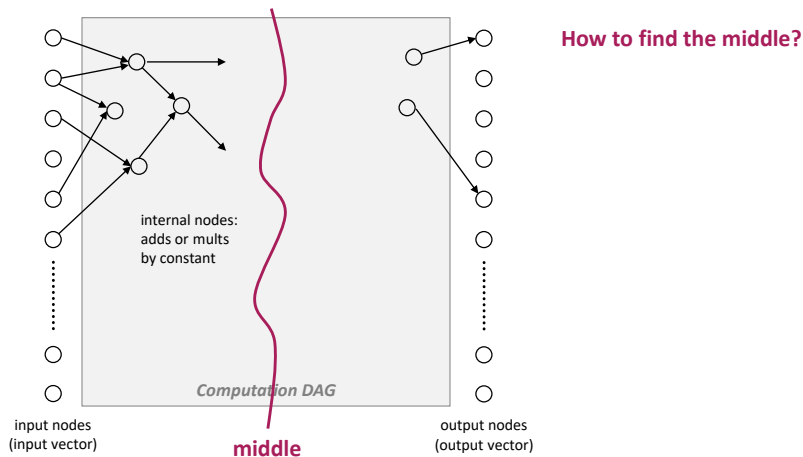


- Determines in which sequence the DAG is unparsed to C (topological sort of the DAG)
Goal: minimize register spills
- A 2-power FFT has an operational intensity of $I(n) = O(\log(C))$, where C is the cache size [1]
- Implies: For R registers $\Omega(n \log(n)/\log(R))$ register spills
- FFTW's scheduler achieves this (asymptotic) bound **independent** of R

[1] Hong and Kung: "I/O Complexity: The red-blue pebbling game"¹⁷

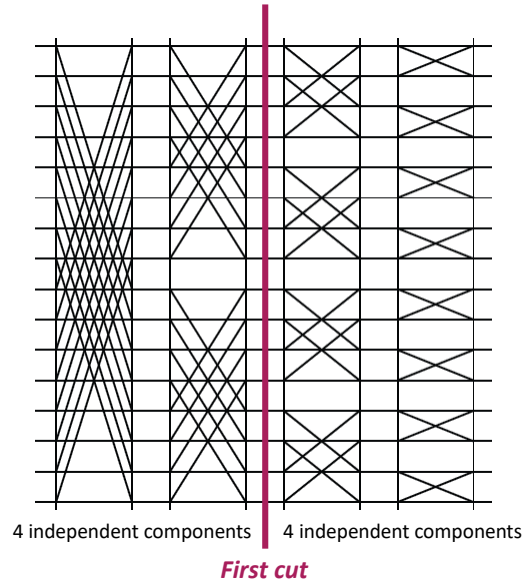
FFT-Specific Scheduler: Basic Idea

- Cut DAG in the middle
- Recurse on the connected components

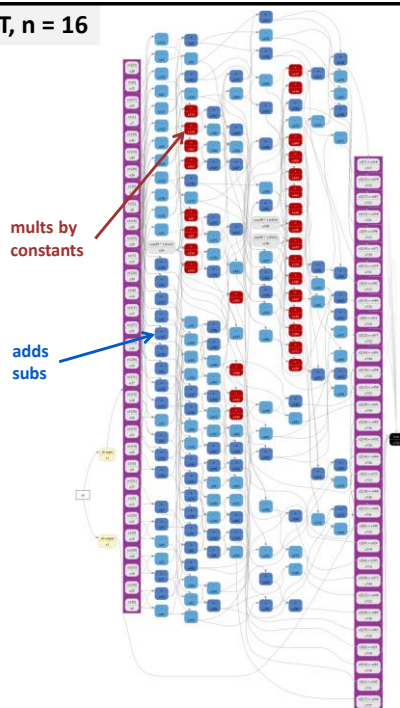


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This is a Sketched/Abstracted DAG



FFT, n = 16



```
typedef struct {
    double* input;
    double* output;
} spiral_t;

const double x788[] = { 1.0, 0.9238795325112867, 0.70710678118654,
const double x789[] = { -0.0, 0.3826834323650898, 0.70710678118654,
void staged(spiral_t* x0) {
    double* x2 = x0->output;
    double* x1 = x0->input;
    double x6 = x1[0];
    double x22 = x1[16];
    double x38 = x6 + x22;
    double x14 = x1[8];
    double x30 = x1[24];
    double x46 = x14 + x30;
    double x343 = x38 + x46;
    double x10 = x1[4];
    double x26 = x1[20];
    double x42 = x10 + x26;
    double x18 = x1[12];
    double x34 = x1[28];
    double x50 = x18 + x34;
    double x344 = x42 + x50;
    double x345 = x343 + x344;
    double x8 = x1[2];
    double x24 = x1[18];
    double x115 = x8 + x24;
    double x16 = x1[10];
    double x32 = x1[26];
    double x123 = x16 + x32;
    double x346 = x115 + x123;
    double x12 = x1[6];
    double x28 = x1[22];
    double x119 = x12 + x28;
    double x20 = x1[14];
    double x36 = x1[30];
    double x127 = x20 + x36;
    double x347 = x119 + x127;
    double x348 = x346 + x347;
    double x349 = x345 + x348;
    x2[0] = x349;
    double x7 = x1[1];
    double x23 = x1[17];
    double x39 = x7 + x23;
    double x15 = x1[9];
    double x31 = x1[25];
    double x47 = x15 + x31;
    double x76 = x39 + x47;
    double x11 = x1[5];
    double x27 = x1[21];
    double x43 = x11 + x27;
    double x19 = x1[13];
    double x35 = x1[29];
    double x51 = x19 + x35;
    double x80 = x43 + x51;
    double x88 = x76 + x80;
```

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Codelet Examples

- Notwiddle 2 (DFTrec)
- Notwiddle 3 (DFTrec)
- Twiddle 3 (DFTscaled)
- Notwiddle 32 (DFTrec)
- **Code style:**
 - Single static assignment (SSA)
 - Scoping (limited scope where variables are defined)

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5: Adaptivity

Choices used for platform adaptation

```
// code sketch
void DFT(int n, cpx *x, cpx *y) {
  if (use_base_case(n))
    DFTbc(n, x, y); // use base case
  else {
    int k = choose_dft_radix(n); // ensure k <= 32
    int m = n/k;
    for (int i = 0; i < k; ++i)
      DFTrec(m, x + i, y + m*i, k, 1); // implemented as DFT(...) is
    for (int j = 0; j < m; ++j)
      DFTscaled(k, y + j, t[j], m); // always a base case
  }
}
```

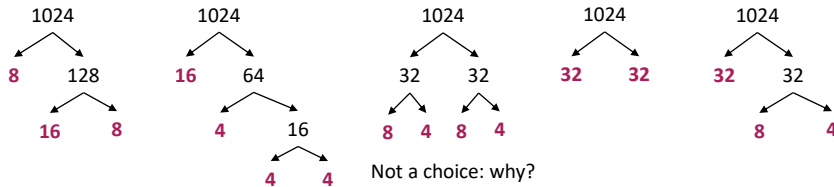
```
d = DFT_init(1024); // compute constant table; search for best recursion
d(x, y);           // use many times
```

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5: Adaptivity

```
d = DFT_init(1024); // compute constant table; search for best recursion
d(x, y);             // use many times
```

Choices: $\text{DFT}_{km} = (\text{DFT}_k \otimes \text{I}_m) T_m^{km} (\text{I}_k \otimes \text{DFT}_m) L_k^{km}$



Base case = generated codelet is called

- Exhaustive search to expensive
- Solution: Dynamic programming

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FFTW: Further Information

- Previous Explanation: FFTW 2.x
- FFTW 3.x:
 - Support for SIMD/threading
 - Flexible interface to handle FFT variants (real/complex, strided access, sine/cosine transforms)
 - Complicates significantly the interfaces actually used and increases the size of the search space

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	MMM <i>Atlas</i>	Sparse MVM <i>Sparsity/Bebop</i>	DFT <i>FFTW</i>
Cache optimization			
Register optimization			
Optimized basic blocks			
Other optimizations			
Adaptivity			

	MMM <i>Atlas</i>	Sparse MVM <i>Sparsity/Bebop</i>	DFT <i>FFTW</i>
Cache optimization	Blocking	Blocking (rarely useful)	Recursive FFT, fusion of steps
Register optimization	Blocking	Blocking (changes sparse format)	Scheduling of small FFTs
Optimized basic blocks	Unrolling, scalar replacement and SSA, scheduling, simplifications (for FFT)		
Other optimizations	—	—	Precomputation of constants
Adaptivity	Search: blocking parameters	Search: register blocking size	Search: recursion strategy