

# Advanced Systems Lab

Spring 2020

*Lecture:* Memory bound computation, sparse linear algebra, OSKI

**Instructor:** Markus Püschel, Ce Zhang

**TA:** Joao Rivera, Bojan Karlas, several more



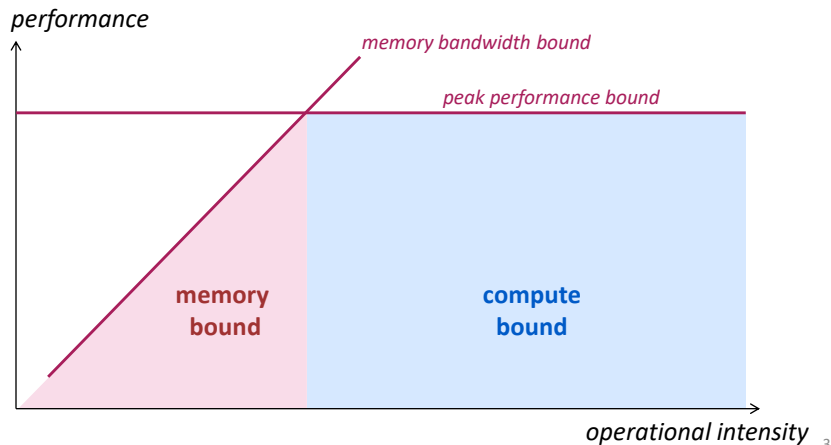
Eidgenössische Technische Hochschule Zürich  
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## Overview

- Memory bound computations
- Sparse linear algebra, OSKI

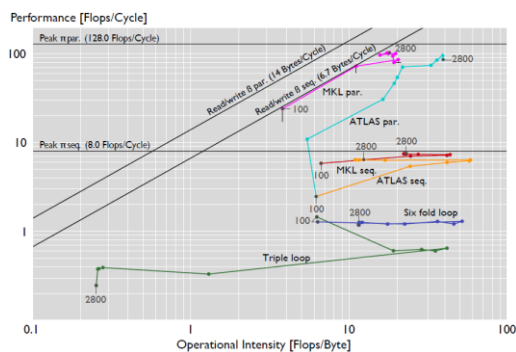
# Memory Bound Computation

- Data movement, not computation, is the bottleneck
- Typically: Computations with operational intensity  $I(n) = O(1)$



## Memory Bound Or Not? Depends On ...

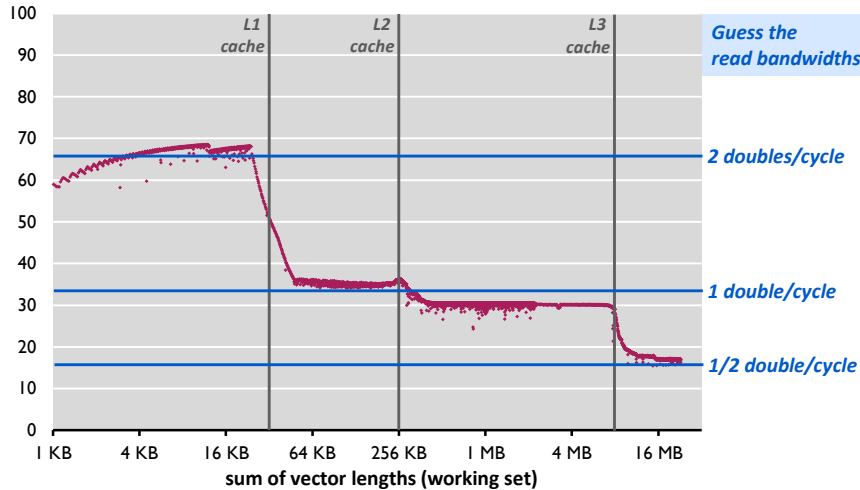
- The computer
  - Memory bandwidth
  - Peak performance
- How it is implemented
  - Good/bad locality
  - SIMD or not
- How the measurement is done
  - Cold or warm cache
  - In which cache data resides
  - See next slide



## Example: BLAS 1, Warm Data & Code

$z = x + y$  on Core i7 (Nehalem, one core, no SSE), icc 12.0 /O2 /fp:fast /Qipo

Percentage peak performance (peak = 1 add/cycle)



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## Sparse Linear Algebra

- Sparse matrix-vector multiplication (MVM)

- Sparsity/Bebop/OSKI

- References:

- Eun-Jin Im, Katherine A. Yelick, Richard Vuduc. *SPARSITY: An Optimization Framework for Sparse Matrix Kernels*, *Int'l Journal of High Performance Comp. App.*, 18(1), pp. 135-158, 2004
- Vuduc, R.; Demmel, J.W.; Yelick, K.A.; Kamil, S.; Nishtala, R.; Lee, B.; *Performance Optimizations and Bounds for Sparse Matrix-Vector Multiply*, pp. 26, Supercomputing, 2002
- [Sparsity/Bebop](#) website

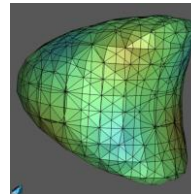
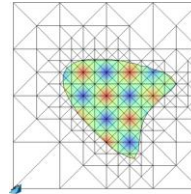
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# Sparse Linear Algebra

- Very different characteristics from dense linear algebra (LAPACK etc.)

- Applications:

- finite element methods
- PDE solving
- physical/chemical simulation (e.g., fluid dynamics)
- linear programming
- scheduling
- signal processing (e.g., filters)
- ...



- Core building block: *Sparse MVM*

Graphics: [http://aam.mathematik.uni-freiburg.de/IAM/homepages/clays/projects/unfitted-meshes\\_en.html](http://aam.mathematik.uni-freiburg.de/IAM/homepages/clays/projects/unfitted-meshes_en.html)

## Sparse MVM (SMVM)

- $y = y + Ax$ ,  $A$  sparse but known (below  $A$  is square)

$$\begin{array}{c} \text{K nonzero entries} \\ \begin{array}{c} \text{---} \\ \text{y} \end{array} = \begin{array}{c} \text{---} \\ \text{y} \end{array} + \begin{array}{c} \text{---} \\ \text{A} \end{array} \bullet \begin{array}{c} \text{---} \\ \text{x} \end{array} \end{array}$$

- Typically executed many times for fixed  $A$
- What is reused (possible temporal locality)?
- Upper bound on operational intensity?  $I(n) \leq 2K/8(K + 3n) \leq 1/4$

# Storage of Sparse Matrices

- **Standard storage is obviously inefficient: Many zeros are stored**
  - Unnecessary operations
  - Unnecessary data movement
  - Bad operational intensity
- **Several sparse storage formats are available**
- **Popular for performance: Compressed sparse row (CSR) format**

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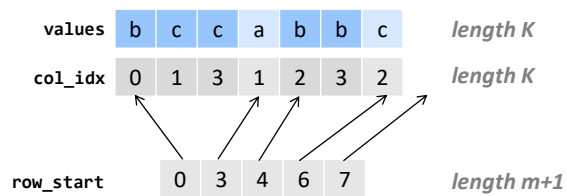
## CSR

- **Assumptions:**
  - A is  $m \times n$
  - K nonzero entries

**A as matrix**

b	c		c
	a		
		b	b
		c	

**A in CSR:**



- **Storage:**
  - K doubles + (K+m+1) ints =  $\Theta(\max(K, m))$
  - Typically:  $\Theta(K)$

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# Sparse MVM Using CSR

$y = y + Ax$

```
void smvm(int m, const double* values, const int* col_idx,
          const int* row_start, double* x, double* y)
{
    int i, j;
    double d;

    /* loop over m rows */
    for (i = 0; i < m; i++) {
        d = y[i]; /* scalar replacement since reused */

        /* loop over non-zero elements in row i */
        for (j = row_start[i]; j < row_start[i+1]; j++)
            d += values[j] * x[col_idx[j]];
        y[i] = d;
    }
}
```

CSR + sparse MVM: Advantages?

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## CSR

### ■ Advantages:

- Only nonzero values are stored
- All three arrays for A (**values**, **col\_idx**, **row\_start**) accessed consecutively in MVM (good spatial locality)
- Good temporal locality with respect to y

### ■ Disadvantages:

- Insertion into A is costly
- Poor temporal locality with respect to x

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## Impact of Matrix Sparsity on Performance

- **Addressing overhead (dense MVM vs. dense MVM in CSR):**
  - ~ 2x slower (example only)
- **Fundamental difference between MVM and sparse MVM (SMVM):**
  - Sparse MVM is input *dependent* (sparsity pattern of A)
  - Changing the order of computation (blocking) requires changing the data structure (CSR)

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## Bebop/Sparsity: SMVM Optimizations

- **Idea:** Blocking for registers
- **Reason:** Reuse x to reduce memory traffic
- **Execution:** Block SMVM  $y = y + Ax$  into micro MVMs
  - Block size  $r \times c$  becomes a parameter
  - Consequence: Change A from CSR to  $r \times c$  block-CSR (BCSR)
- **BCSR:** Next slide

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## BCSR (Blocks of Size $r \times c$ )

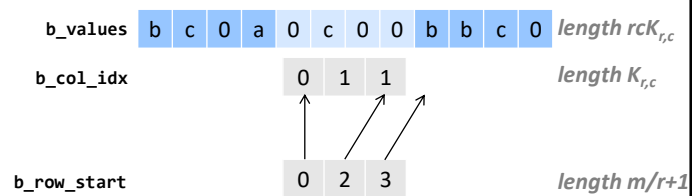
### Assumptions:

- A is  $m \times n$
- Block size  $r \times c$
- $K_{r,c}$  nonzero blocks

A as matrix ( $r = c = 2$ )

b	c		c
	a		
		b	b
		c	

A in BCSR ( $r = c = 2$ ):



### Storage:

- $rcK_{r,c}$  doubles +  $(K_{r,c} + m/r + 1)$  ints =  $\mathcal{O}(rcK_{r,c})$
- $rcK_{r,c} \geq K$

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## Sparse MVM Using 2 x 2 BCSR

```
void smvm_2x2(int bm, const int *b_row_start, const int *b_col_idx,
               const double *b_values, double *x, double *y)
{
    int i, j;
    double d0, d1, c0, c1;

    /* loop over bm block rows */
    for (i = 0; i < bm; i++) {
        d0 = y[2*i]; /* scalar replacement since reused */
        d1 = y[2*i+1];

        /* dense micro MVM */
        for (j = b_row_start[i]; j < b_row_start[i+1]; j++, b_values += 2*2) {
            c0 = x[2*b_col_idx[j]+0]; /* scalar replacement since reused */
            c1 = x[2*b_col_idx[j]+1];
            d0 += b_values[0] * c0;
            d1 += b_values[2] * c0;
            d0 += b_values[1] * c1;
            d1 += b_values[3] * c1;
        }
        y[2*i] = d0;
        y[2*i+1] = d1;
    }
}
```

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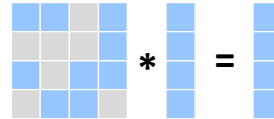
# BCSR

## Advantages:

- Temporal locality with respect to x and y
- Reduced storage for indexes

## Disadvantages:

- Storage for values of A increased (zeros added)
- Computational overhead (also due to zeros)

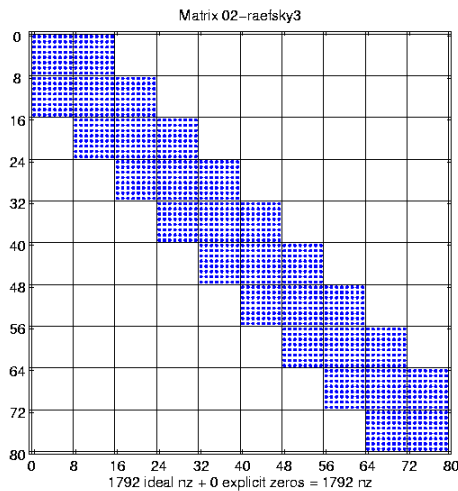


## Main factors (since memory bound):

- **Plus:** increased temporal locality on x + reduced index storage = reduced memory traffic
- **Minus:** more zeros = increased memory traffic

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# Which Block Size (r x c) is Optimal?

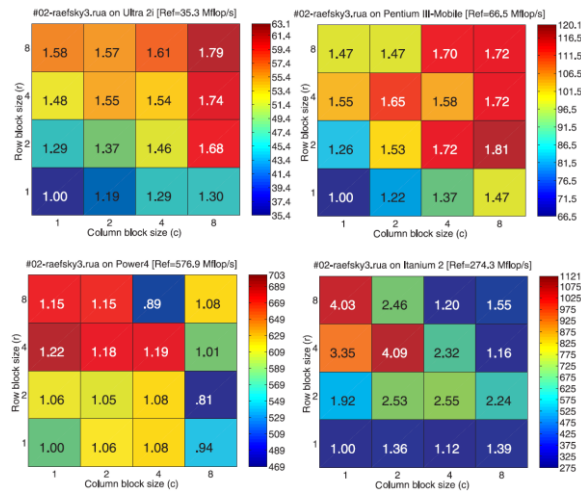


## Example:

- 20,000 x 20,000 matrix (only part shown)
- Perfect 8 x 8 block structure
- No overhead when blocked r x c, with r, c divides 8

source: R. Vuduc, LLNL

# Speed-up Through r x c Blocking



- machine dependent
- hard to predict

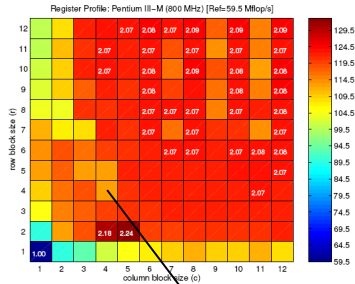
Source: Eun-Jin Im, Katherine A. Yelick, Richard Vuduc. SPARSITY: An Optimization Framework for Sparse Matrix Kernels, Int'l Journal of High Performance Comp. App., 18(1), pp. 135-158, 2004

## How to Find the Best Blocking for given A?

- Best block size is hard to predict (see previous slide)
- **Solution 1:** Searching over all r x c within a range, e.g.,  $1 \leq r, c \leq 12$ 
  - Conversion of A in CSR to BCSR roughly as expensive as 10 SMVMs
  - Total cost: 1440 SMVMs
  - Too expensive
- **Solution 2: Model**
  - Estimate the gain through blocking
  - Estimate the loss through blocking
  - Pick best ratio

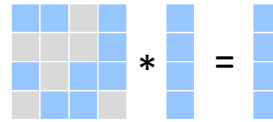
## Model: Example

### Gain by blocking (dense MVM)



1.4

### Overhead (average) by blocking



$$16/9 = 1.77$$

$$1.4/1.77 = 0.79 \text{ (no gain)}$$

*Model:* Doing that for all  $r$  and  $c$  and picking best

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## Model

- **Goal:** find best  $r \times c$  for  $y = y + Ax$
- **Gain** through  $r \times c$  blocking (estimation):

$$G_{r,c} = \frac{\text{dense MVM performance in } r \times c \text{ BCSR}}{\text{dense MVM performance in CSR}}$$

dependent on machine, independent of sparse matrix

- **Overhead** through  $r \times c$  blocking (estimation)
- scan part of matrix A

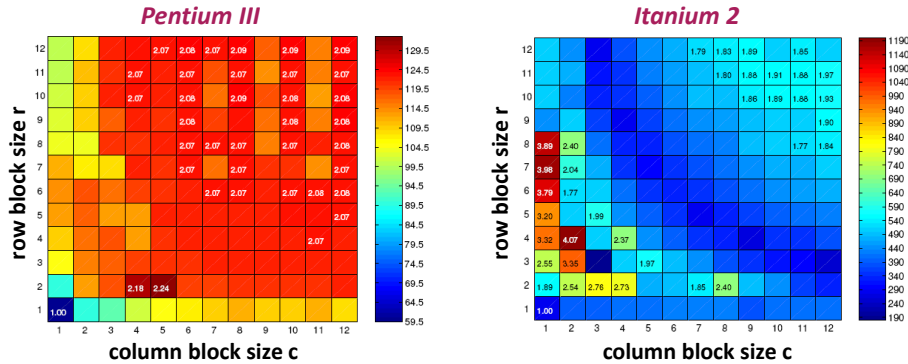
$$O_{r,c} = \frac{\text{number of matrix values in } r \times c \text{ BCSR}}{\text{number of matrix values in CSR}}$$

independent of machine, dependent on sparse matrix

- **Expected gain:**  $G_{r,c}/O_{r,c}$

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## Gain from Blocking (Dense Matrix in BCSR)



- machine dependent
- hard to predict

Source: Eun-Jin Im, Katherine A. Yelick, Richard Vuduc. SPARSITY: An Optimization Framework for Sparse Matrix Kernels, *Int'l Journal of High Performance Comp. App.*, 18(1), pp. 135-158, 2004

## Typical Result

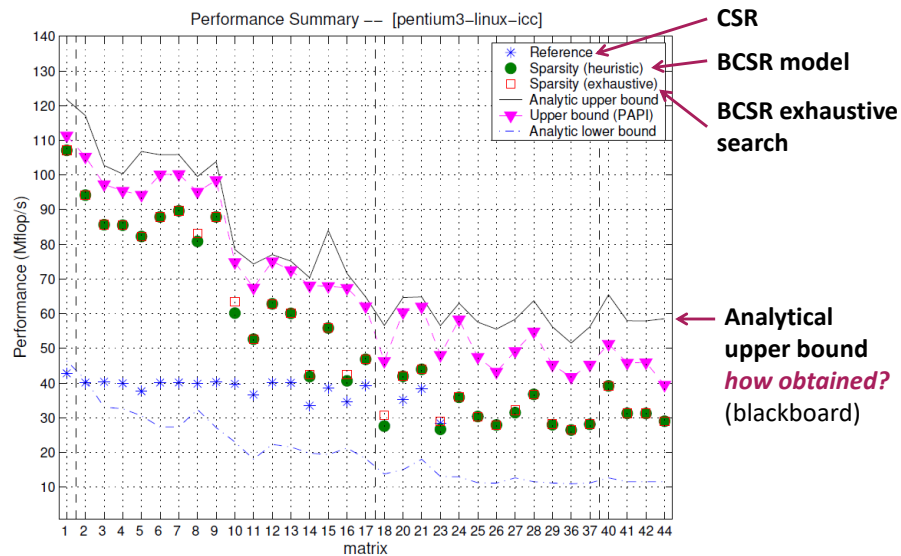


Figure: Eun-Jin Im, Katherine A. Yelick, Richard Vuduc. SPARSITY: An Optimization Framework for Sparse Matrix Kernels, *Int'l Journal of High Performance Comp. App.*, 18(1), pp. 135-158, 2004

## Principles in Bebop/Sparsity Optimization

- **Optimization for memory hierarchy = increasing locality**
  - Blocking for registers (micro-MVMs)
  - *Requires change of data structure for A*
  - Optimizations are *input dependent* (on sparse structure of A)
- **Fast basic blocks for small sizes (micro-MVM):**
  - Unrolling + scalar replacement
- **Search for the fastest over a relevant set of algorithm/implementation alternatives (parameters  $r, c$ )**
  - *Use of performance model* (versus measuring runtime) to evaluate expected gain

*Different from ATLAS*

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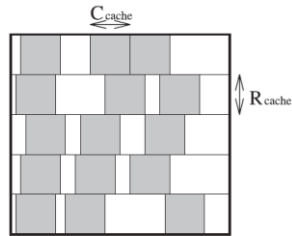
## SMVM: Other Ideas

- Cache blocking
- Value compression
- Index compression
- Pattern-based compression
- Special scenario: Multiple inputs

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# Cache Blocking

- Idea: divide sparse matrix into blocks of sparse matrices



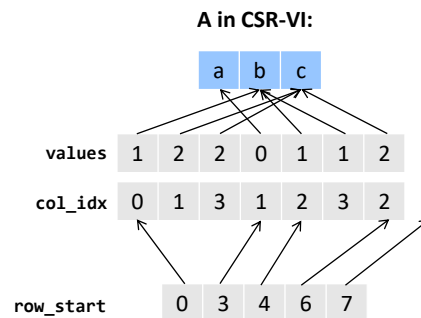
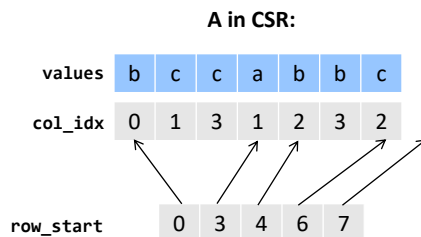
- Experiments:
  - Requires very large matrices (x and y do not fit into cache)
  - Speed-up up to 2.2x, only for few matrices, with 1 x 1 BCSR

Figure: Eun-Jin Im, Katherine A. Yelick, Richard Vuduc. SPARSITY: An Optimization Framework for Sparse Matrix Kernels, Int'l Journal of High Performance Comp. App., 18(1), pp. 135-158, 2004

# Value Compression

- **Situation:** Matrix A contains many duplicate values
- **Idea:** Store only unique ones plus index information

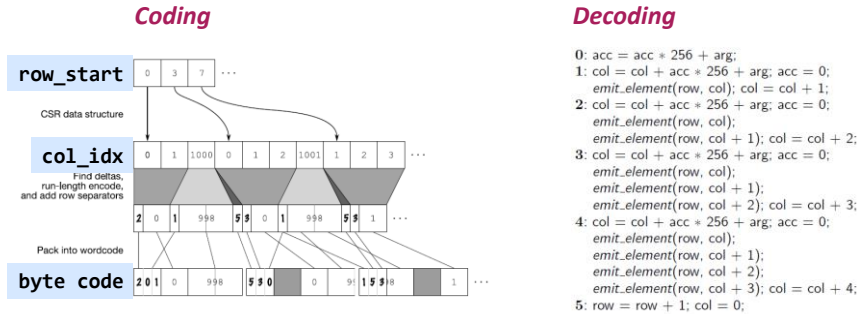
b	c		c
	a		
		b	b
		c	



Kourtis, Goumas, and Koziris, Improving the Performance of Multithreaded Sparse Matrix-Vector Multiplication using Index and Value Compression, pp. 511-519, ICPP 2008

# Index Compression

- **Situation:** Matrix A contains sequences of nonzero entries
- **Idea:** Use special byte code to jointly compress col\_idx and row\_start



Willcock and Lumsdaine, Accelerating Sparse Matrix Computations via Data Compression, pp. 307-316, ICS 2006

# Pattern-Based Compression

- **Situation:** After blocking A, many blocks have the same nonzero pattern
- **Idea:** Use special BCSR format to avoid storing zeros; needs specialized micro-MVM kernel for each pattern

A as matrix

b	c		c
	a		
		b	b
		c	

Values in 2 x 2 BCSR

b	c	0	a	0	c	0	0	b	b	c	0
---	---	---	---	---	---	---	---	---	---	---	---

Values in 2 x 2 PBR

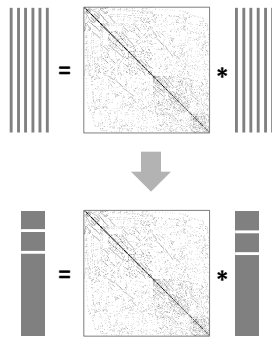
b	c	a	c	b	b	c
---	---	---	---	---	---	---

+ bit string: 1101 0100 1110

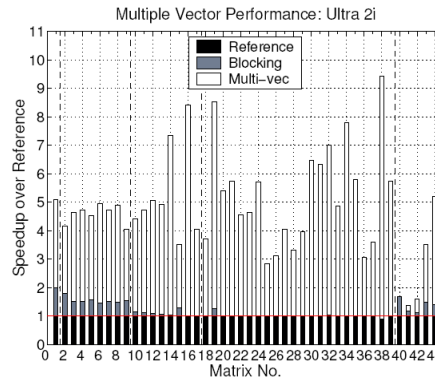
Belgin, Back, and Ribbens, Pattern-based Sparse Matrix Representation for Memory-Efficient SMVM Kernels, pp. 100-109, ICS 2009

## Special Scenario: Multiple Inputs

- Situation: Compute SMVM  $y = y + Ax$  for several independent  $x$
- Experiments: up to 9x speedup for 9 vectors



enables blocking across  
MVMs like MMM



Source: Eun-Jin Im, Katherine A. Yelick, Richard Vuduc. SPARSITY: An Optimization Framework for Sparse Matrix Kernels, *Int'l Journal of High Performance Comp. App.*, 18(1), pp. 135-158, 2004