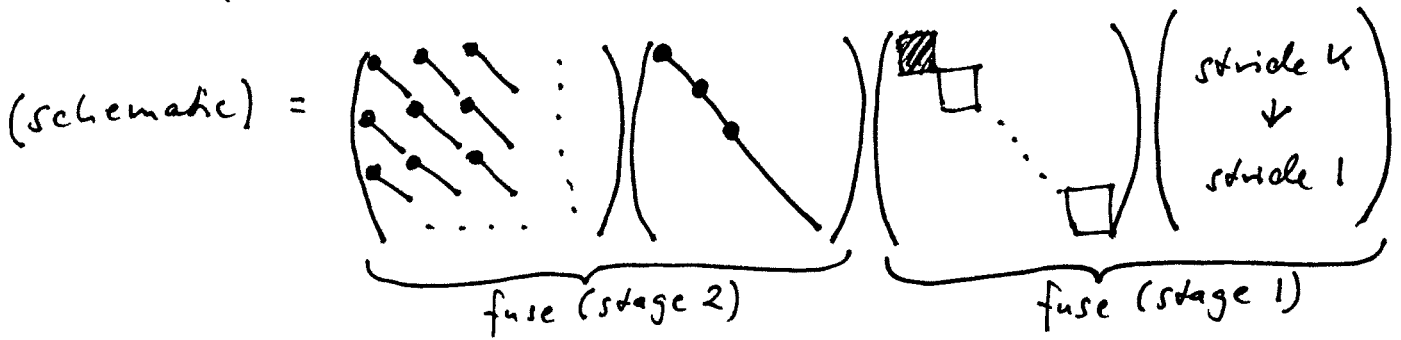


FFT, fast implementation (following FFWL x)

1.) Choice of algorithm: Choose recursive FFT, not iterative FFT

2.) Locality optimization:

$$DFT_{km} = (DFT_k \otimes I_m) T_m^{km} (I_k \otimes DFT_m) L_k$$



compute m many

$$DFT_k \cdot D$$

part of
diagonal T_m^{km}

at stride m
(input and output)

- writes to the same location it reads from
- in-place

$$DFT_{scaled}(k, *x, *d, stride)$$

↑ size ↑ input vector ↑ diagonal elements

this interface cannot handle arbitrary recursions
→ in FFWL a base case



compute k many DFT_m
with input stride k and
output stride 1 .

- writes to different location it reads from
- out-of-place

$$DFT_{rec}(m, *x, *y, inside, outside)$$

↑ size ↑ input vector ↑ output vector

this interface can handle arbitrary recursions

Pseudo code: $DFT(n, x, y) = DFT_{rec}(n, x, y, 1, 1)$

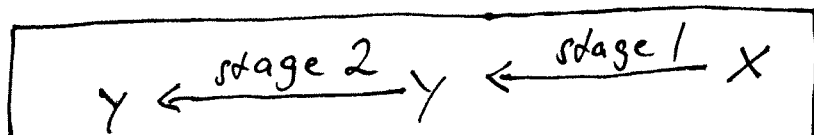
```
for (int i = 0; i < k; ++i)
```

```
    DFTrec(m, y + m*i, x + i, k, 1); // implemented as DFT(...) is
```

```
for (int j = 0; j < m; ++j)
```

```
    DFTscaled(k, y + j, t[j], m); // always a base case
```

↑
precomputed twiddles



3.) Constants:

The matrix T_m^{km} yields multiplications by constants:

$$y_i = \omega_n^k x_i$$

some root of unity

which in the code, on real numbers, gives multiplications by sines and cosines

$$y_i = \sin\left(\frac{i \cdot \pi}{128}\right) x_i \quad \text{etc.}$$

Problem: Computing $\sin(\dots)$ is very expensive (HW 2)

Solution:

- precompute once
- reuse many times
- assumes a transform for one size is used many times

Changes library interface:

```
d = dft-plan(1024); // precomputes constants
d(*x, *y); // computes DFT, size 1024
```

4.) Fast basic blocks

We do not want to recurse all the way to $n=2$

- function call overhead
- suboptimal register use

Solution:

- unroll recursion for small enough n
- practice shows $n \leq 32$ is sufficient
- requires 62 functions! Why?

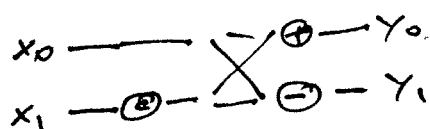
FFTW: "codelet" generator for small size FFT



a.) DAG generator recursively

- generates DAG from stored algorithms
- DAGs have only adds/subs/mults by const

Example:



$$\begin{pmatrix} y_0 \\ y_1 \end{pmatrix} = \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} \begin{pmatrix} 1 \\ c \end{pmatrix} \begin{pmatrix} x_0 \\ x_1 \end{pmatrix}$$

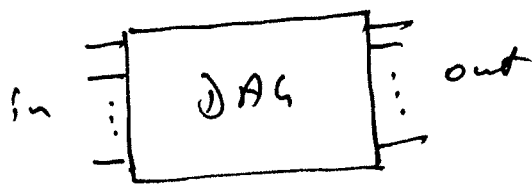
b.) Simplifier

- simplifies multi by 0, 1, -1
- distributivity law: $kx + ky = k(x+y)$
- canonicalization: $x-y, y-x \rightarrow x-y, -(x-y)$
- common subexpression elimination (CSE)
- all constants are made positive:
reduces register pressure
- CSE also on transposed DAG

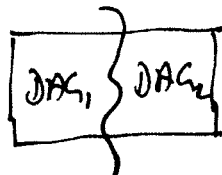
c.) Scheduler:

Theoretical result: 2-power FFT needs
 $\Omega\left(\frac{n \log(n)}{R}\right)$ register spills
for R registers

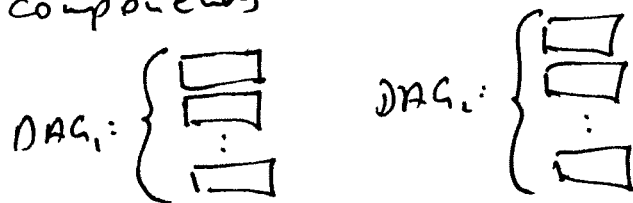
The following algorithm achieves that:



step 1: cut DAG in middle (how to do that)



step 2: DAG₁, DAG₂ ~~are~~ decompose into independent components



schedule these recursively

Finally: output straight line, SSA code